

Engineering Physics Theory



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Rigid Body And Rotational Dynamics Centripetal Force:

For a body of mass m moving in a circle of radius r with a uniform speed v and angular velocity has an acceleration $v^2/r = r\omega^2$ towards the centre and force mv^2/r acts on it.

Equations Of Motion:

The equations of motion for rotational motion are similar to those of linear motion.

$$\begin{split} \omega_f &= \omega_i + \alpha t \\ \theta &= \omega_i t + (1/2)\alpha t^2 \\ \omega_{f^2} &= \omega_{i^2} + 2\alpha \theta \\ \theta &= (\omega_f + \omega_i)t/2 \end{split}$$
These apply to the case of constant acceleration.

Moment Of Inertia:

Moment of inertia is the **inertial equivalent of mass** in rotational dynamics.

Moment of inertia of a particle of mass m rotating in a circle of radius r has moment of inertia mr^2 . For a group of particles, it is given by Σmr^2 .

Torque:

Torque causes rotation.

Consider a force F acting on a body at an angle to the radius of circle in which it rotates. The torque acting at a distance r from the point of rotation is $Frsin\theta$.



Representation of torque force

The maximum torque (Fr) acts on a body when the force applied is perpendicular to the radius.

Couple:

A couple is said to act on a body when two forces of equal magnitude act on the body in opposite directions. For a non-zero couple, the forces should not act on a straight line. Here the **net force acting is zero**. So, there will be no linear motion produced by the couple.

The magnitude of a couple whose magnitude of force is F and distance between the lines of action of forces is d is Fd.

When a torque T acts on a body, the angular acceleration produced is $\alpha = T/I$.

Consider a force F acting on a body at a distance r from its centre of mass. Discuss how it can be divided into a combination of linear motion

and rotational motion by considering a force and a couple individually and then adding them up.

Rotational Equilibrium:

A body is said to be in rotational equilibrium if the net torque acting on it is zero. Then the angular velocity is either zero or is constant.

E.g.: A ladder leans on a frictionless wall. Find the forces acting on the ladder due to the wall and the ground.



Answer. Balancing the forces, Vertical: Rg=W Horizontal: Rw=F The ladder is in rotational equilibrium. So, the torques should be balanced about any point. Balancing torques about the bottom of ladder,

Torques in clockwise direction=Torques acting in counter clockwise direction $W(L/2) \sin\theta = R_w L \cos\theta$ $R_w = F = (W/2) \tan\theta$

Angular Momentum:

Angular momentum of a body of moment of inertia I rotating at an angular velocity ω is $I\omega$.

When no external torque acts on a system, the total angular momentum of the system remains constant. This is called **law of conservation of angular momentum**.

Rotational Kinetic Energy:

The kinetic energy due to rotation of a body of moment of inertia I rotating with an angular velocity ω is (1/2) $I\omega^2$.

Work Done:

Work done on a body by a torque T that acts along an angular displacement θ is $T\theta$.

Rolling And Sliding:

When a ball moves on a perfectly frictionless surface, it slides – there is no relation between angular motion and linear motion of the ball and both of them function independently.

When there is friction, the ball may roll – the point of contact of the ball with the surface remains at rest temporarily.

If the ball of radius r rolls with an angular velocity ω and has a linear velocity v, then

- v=ωr
- Every point on the surface of the ball has a tangential velocity and a velocity along the direction of linear motion, both magnitudes being equal to v.
- The top most part of the ball has a velocity 2v and the bottom most part remains at rest.
- The total kinetic energy of the ball is is $(1/2)I\omega^2 + (1/2)mv^2$.

E.g.: A solid ball, of radius of 45 mm, rolls down an inclined plane of length 2.5 m. The sphere takes a time of 6.0 s to roll down the plane. Assume that the ball does not slip.

The moment of inertia, I, of a solid ball of mass M and radius R is given by $I = (2/5)MR^2$

- a. Calculate the velocity of the sphere as it reaches the end of the plane.
- b. Calculate the angular velocity of the sphere as it reaches the end of the plane.
- c. Determine the angle of inclination of the plane.
- d. Comment on whether the assumption that the ball does not slip was appropriate in this instance.

Answer.

a) For the ball, the linear acceleration is $a = (2s/t^2)$ =(2×2.5)/6² =0.14ms⁻²

So, the linear velocity of the ball at the end is $v = at = 0.14 \times 6 = 0.84ms^{-1}$.

b) The angular velocity is $\omega = v/r = 18.7 rads^{-1}$ **c)** From law of conservation of energy,

$$mgh = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2$$

Substituting $I = \frac{2}{5}MR^2$ and $v = r\omega$, we get

$$h = \frac{v^2}{2g} \left(\frac{2}{5} + 1\right) = 0.05m$$

The angle made is
$$\theta = \sin^{-1} \frac{h}{L} = \sin^{-1} \frac{0.05}{2.5} = 1.1^{\circ}$$

d) This angle is very small and there is no problem with assuming that the ball rolls without slipping.

Thermodynamics

Thermodynamics mainly focuses on extraction of work from heat.

Internal Energy Of The Gas (U):

The total kinetic energy of a gas is the **total kinetic energy** of all molecules of the gas. It is assumed that there is no potential energy between gas molecules.

The internal energy of n moles of gas at a temperature T is (3/2)nRT.

Work Done By A Gas (W):

Consider a gas contained in a cylinder at a pressure P undergoing a volume change ΔV . Then the work done by the gas is $P\Delta V$. Graphically, this is equal to the area under the curve in Pressure-Volume graph.

First Law Of Thermodynamics:

The first law of thermodynamics states that energy can neither be created nor destroyed but can only be transformed from one form to another form.

 $Q = \Delta U + W$

Sign Convention:

Heat: Heat supplied to gas is positive. Work: Work done by gas is positive when volume increases. Work done on the gas is the opposite. (Work in the equation of first law is work done by the gas)

Internal energy: Change in internal energy is positive if the temperature increases.

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Types Of Processes:

Isobaric – constant pressure process: Work done is $P\Delta V$. For compression,



Isochoric - Constant volume process: ΔV is zero. So, work done is zero. First law equation reduces to $Q = \Delta U$ When volume increases, the P-V graph is as follows

Isothermal – constant temperature process: ΔT is zero. So, internal energy change is zero. $\Delta U = 0, Q = \Delta W$ An ideal gas follows PV = nRT. So, in an isothermal process, PV=constant.

Adiabatic Process:

No heat is exchanged. Process occurs in an isolated system. $\Delta Q = 0, \Delta U + \Delta W = 0$



Cyclic Processes:

A cyclic process is one in which the initial state is same as the final state. On a P-V diagram, it forms a closed loop.





As the initial and final temperatures are same, the **net change in internal energy is zero**. These type of processes occur mostly in heat engines where heat is converted to work.

Heat Engine:

A heat engine generally involves four processes.

- 1. Heat intake
- 2. Work output
- 3. Heat rejection
- 4. Work input

The net work done in a cyclic process is the area enclosed by the curve in P-V diagram.

The efficiency of a heat engine is given by the ratio of net work

$$\eta = \frac{W}{Q_H} = \frac{Q_H - Q_C}{Q_H} = 1 - \frac{Q_C}{Q_H}$$

done by heat taken.

Carnot Cycle:

A carnot cycle is the most efficient cycle which converts heat to work working between two fixed temperature reservoirs which provide and take heat during the cycle. In a carnot engine, the heat is exchanged at constant temperature and work exchange is done without any heat change. The P-V diagram looks like this.

The efficiency is $\mathbb{P} = 1 - (\mathbb{P}_{\mathbb{P}} / \mathbb{P}_{\mathbb{P}}) = 1 - (\mathbb{P}_{\mathbb{P}} / \mathbb{P}_{\mathbb{H}})$

Refrigerator:

When a carnot cycle is operated in reverse, it functions as a refrigerator – takes heat out from a low temperature reservoir and dumps it in a high temperature reservoir with work as input.



a) During the change AB the change in internal energy of the gas is 7.2 kJ.

(i) Calculate the temperature, at B, of the gas.

(ii) Determine the amount of energy transferred during change AB.

b) State why, for the change BC, the change in the internal energy of the gas is numerically the same as that in AB.

c) Calculate:

i) the net work done in one cycle

ii) the efficiency.

Answer.

a)

i) For an ideal gas at constant pressure,

 $V_1/T_1 = V_2/T_2$

ii) $W = P\Delta V = 12.0 \times 10^{5} \times (6 - 2) \times 10^{-3} = 4.8 k J$

The increase in internal energy is 7.2kJ. So, the total energy supplied is $W + \Delta U = 12.0kJ$

b) The internal energy along AC does not change as ther is no change in temperature. In a cyclic process, the net internal change is zero. So, the internal change BC is same in magnitude to that of AB.

c)

i) The net work done is the area enclosed in the graph. From the graph, this is equal to 200J.

ii) Second law of thermodynamics:

 $\eta = W/Q = 2.8/12 = 0.23$

It is not possible to develop a heat engine that converts heat completely to work.

The above statement is the Kelvin-Planck statement of second law states:

It is not possible to develop a heat engine that converts heat completely to work.

It is impossible for heat to be transferred from a cold body to a hot body without any work being done.

The Clausius statement of the law is:

It is impossible for heat to be transferred from a cold body to a hot body without any work being done.

Entropy:

Entropy is the order of randomness of a system.

The increase in entropy of a system when Q amount of heat flows into it at a constant temperature T is Q/T.

Second Law In Terms Of Entropy:

The entropy of a closed system either increases or remains constant in a cyclic process.

Fluids And Their Dynamics

Fluids take the shape of a container and have the ability to flow. **Gases** and **liquids** are collectively called fluids.

Fluid Statics

Density:

Density is the mass per unit volume. $\rho = m/V$

Pressure:

Pressure is the force acting per unit area.

Pressure is a **scalar** and is same in all directions at a point. If the force acting on a surface of area A is F, then the average pressure at that point is F/A.

In a liquid of density whose pressure at the surface is P_0 , the pressure at a point h distance below the surface is $P_0 + \rho gh$.

Pascal's Principle:

The pressure applied at one point in an enclosed point under equilibrium conditions is equally transmitted to all points in the fluid.



Application Pascal's Principle

Consider the situation above. The pressure at the left end is F_x/A_x . This is equal to the pressure on the right end F_y/A_y . This gives:

$$F_x = (A_x F_y) / A_y$$

Varying the ratio , we can lift the load with a small force on the left.

Archimedes' Principle:

The buoyancy acting on an object immersed in a fluid is equal to the weight of fluid displaced by the object.

$$B = V \rho g$$

V is the volume of the object and is the density of fluid.

E.g.: The density of water is $10^{3}kgm^{-3}$ and that of iron is 7.8 × $10^{3}kgm^{-3}$. Calculate the force required to lift a 60kg ball from water.

Answer. The F.B.D of the ball is as follows.



Buoyancy of the ball

 $F_{B} + T = W = 60 \times 9.8 = 588N$

 $F_B = weight of water displaced = \frac{W \rho_w}{\rho_{iron}} = 75.4N$

T = 588 - 75.4 = 512.6N

Fluid Dynamics

Streamlined flow:

In a streamlined flow, the motion of one particle passing through a point is similar to the motion of all points passing through that point. This is also called **laminar flow**. **The continuity equation:**

It is applicable for incompressible liquids only. It is based on the fact that the mass of fluid entering is equal to the mass leaving.

The volume flow rate is constant throughout the flow. At cross sections 1 and 2 of a flow,

$$A_1 v_1 = A_2 v_2$$

Bernoulli's equation:

$(1/2)\rho v^2 + \rho gh + P = constan$

Applications of Bernoulli's equation:

Pitot static tubes: These tubes are used to measure the velocity of a fluid. Two tubes – static and pitot tubes measure the static and dynamic pressure of the fluid. The velocity of the fluid is determined by $v = \sqrt{2g(h_y - h_s)}$.

E.g.: Consider a cylindrical container of uniform area A containing a liquid up to a height H. A small orifice is made at the bottom of the container. Find the velocity of ejected stream from the orifice.



Answer. The orifice is assumed to be sufficiently small so that the velocity of surface of water is zero. The atmospheric pressure is P₀. Applying Bernoulli's principle at the top and at the orifice,

$$\rho gh + P_0 = \frac{1}{2}\rho v^2 + P_0$$
$$v = \sqrt{2gh}$$

Viscosity of fluid:

Viscosity impedes the relative motion between layers of fluids. It is measured in terms of **coefficient of viscosity** (η). In a river-like flow, the bottom-most layer remains at rest with the bed while the top most layer has highest velocity.

Consider two parallel plates of area A separated by a fluid of coefficient of viscosity η by a distance h. The force required to move the upper plate with a velocity v is $\eta A(v/L)$.

Viscosity of liquids decrease with temperature while that of gases increase with temperature.

Stokes law:

When a sphere of radius r falls through a fluid of coefficient of viscosity at a velocity v, the viscous force acting on it is $6\pi\eta rv$.

The **terminal velocity** of a ball whose density is falling through a fluid of density ρ is $v_t = (2r^2g(\sigma-\rho))/9\eta$.

Turbulent flow: Reynolds number of a fluid flow is $R_e = vr\rho/\eta$. Here r is the radius of pipe.

It is a dimensionless number and marks the transition between laminar and turbulent flow.

If the Reynolds number is greater than 2000, then the flow is considered to be turbulent.

Forced Vibrations And Resonance Damped Harmonic Motion:

In the modelling of loaded spring and pendulum motion in previous chapters, it is assumed that no dissipative forces act on it.

The dissipative forces that act in real life mostly are of the form F = -bv.

The equilibrium condition of such an object gives the following equation:

$$ma = -kx - bv$$

Solving this gives,

$$x = ae^{-\frac{bt}{m}}cos\omega t$$

Graphically,

Displacement Displacement Displacement Friend, Millisopher, Guide

The amplitude decreases exponentially with time. The above shown example is **under damped** – the value of bm is small.

The damping is said to be **critical**, when the object reaches equilibrium position and stops at that position. It is said to be **over damped** when the object does not reach equilibrium position at all.



The quality factor:

The quality factor (Q) is a measure of the number of oscillations the system can perform before it runs out of energy. For a large number of oscillations, this is approximately equal to the number of oscillations performed by the system.

 $Q = 2\pi (energy \ stored) / energy \ lost \ per \ cycle$

If Q is high, then the system can perform large number of oscillations without much loss of energy in each cycle.

E.g.: An electrical pendulum clock has a period of 1.0 s. An electrical power supply of 25 mW maintains its constant amplitude. As the pendulum passes its equilibrium position it has kinetic energy of 40 mJ.

Calculate the Q factor for the pendulum clock.

Answer. The pendulum has a frequency of 1.0 Hz. As it is storing 40 mJ, the rate of energy supplied must equal the rate at which energy is lost i.e., the power is supplied at a rate of 25mW.

 $Q = 2\pi \times resonant \ frequency \times \left(\frac{energy \ stored}{power \ loss}\right) = 2\pi \times 1.0 \times \frac{40 \times 10^{-3}}{25 \times 10^{-3}} = 10$

Forced vibration:

When an oscillating system is subjected to a sinusoidal force, then the system oscillates with the frequency of force rather than its natural frequency.

Resonance:

When the driving frequency of the force matches with the natural frequency of the system, then the amplitude of vibration reaches a maximum. This is called resonance.

Effect of damping:

In a lightly damped system, the resonant frequency is almost the same as that of natural frequency. If the system is heavily damped, the resonant frequency is less than natural frequency.

Q factor for a forced, damped oscillator is: $Q = 2\pi \times resonant \ frequency \times (energy \ stored | energy \ lost)$

Resonance curves with various Q factors:



Phase difference between driver and driven:

When the system is in resonance, the driver leads the driven by $\pi/2$ phase.

At a frequency less than resonant frequency, the driver and driven are in phase.

At a frequency greater than resonant frequency, the difference in phase difference is π .

Electrical resonance:

A resistor, conductor and an inductor connected in series forms a damped oscillating system. The resonant frequency depends on the conductance and this can be used to electric signals of certain frequency.

